

# Weed map generation from UAV image mosaics based on crop row detection

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# Our approach

- ▶ Assume that weeds are uniformly distributed
- ▶ Detect crop rows
- ▶ Remove crop rows
- ▶ Remaining vegetation must be weeds

# Image acquisition



Hexacopter

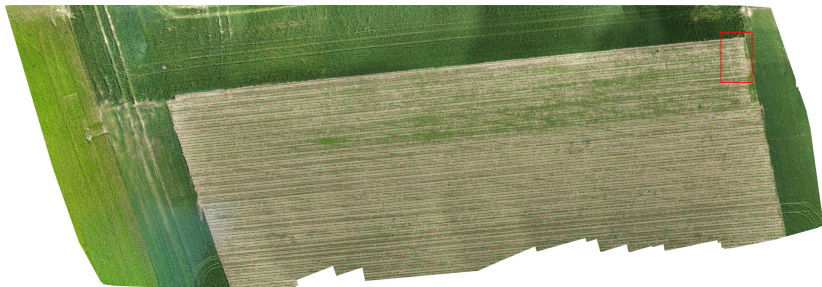
Image acquisition height: 16  
meters



Canon PowerShot G15

Resolution: 4000 x 3000

## Generated mosaic



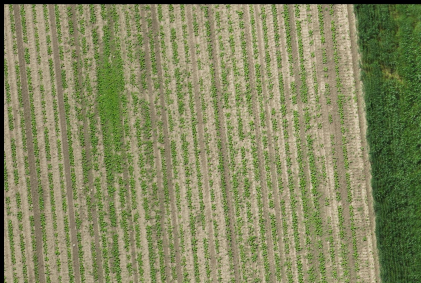
Pix4D is used for assembling the orthomosaic

Dimensions of ortomosaic:  $8206 \times 23713 \sim 195MP$ .

## Zoom on mosaic



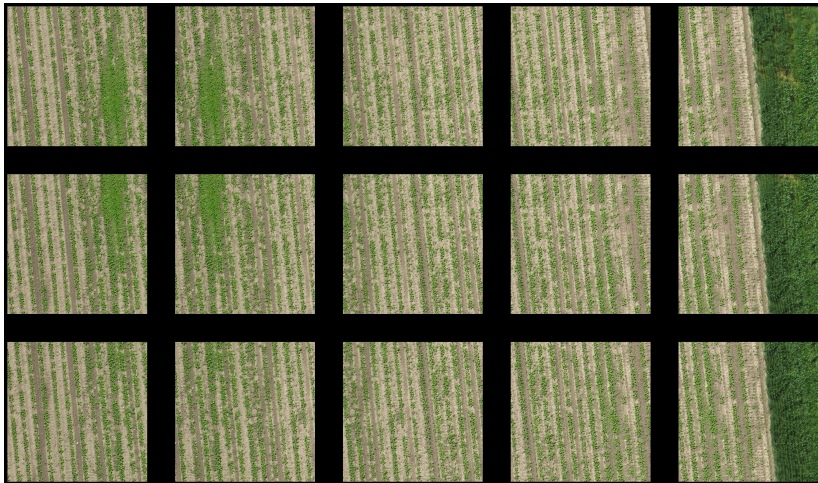
# Extraction of tiles from the mosaic



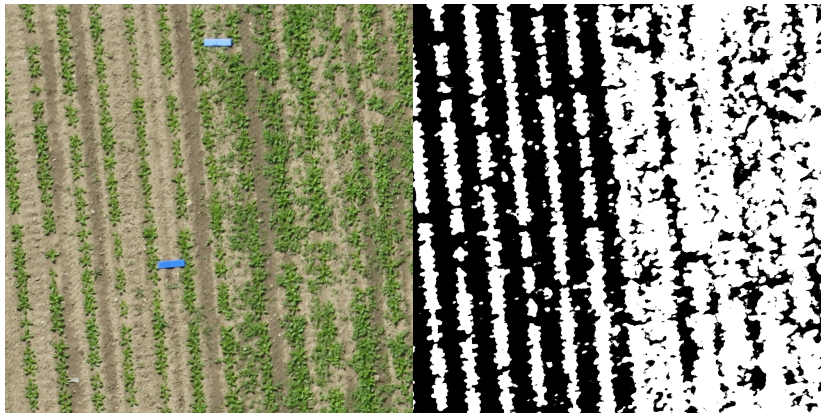
# Extraction of tiles from the mosaic



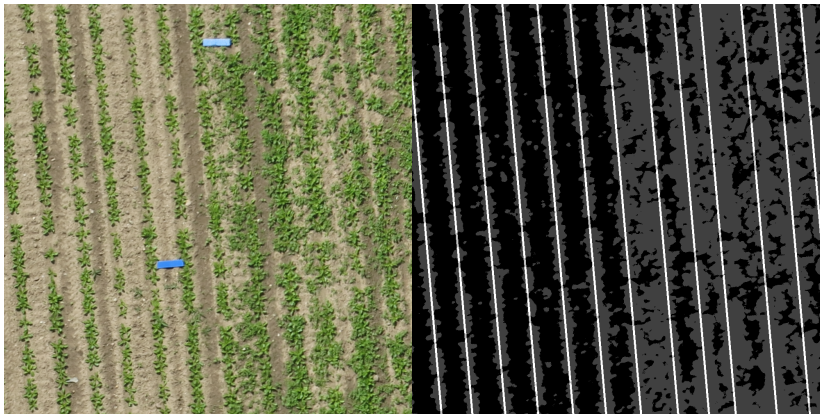
# Extraction of tiles from the mosaic



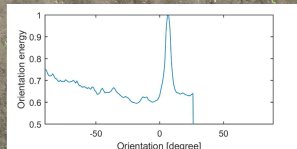
## Locating vegetation – thresholding ExG



# Located crop rows



## Orientation responses



Then we search for the crop row orientation by

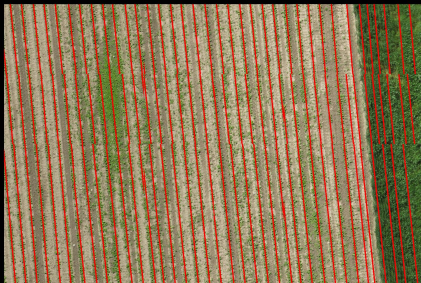
# Combining tiles



# Combining tiles



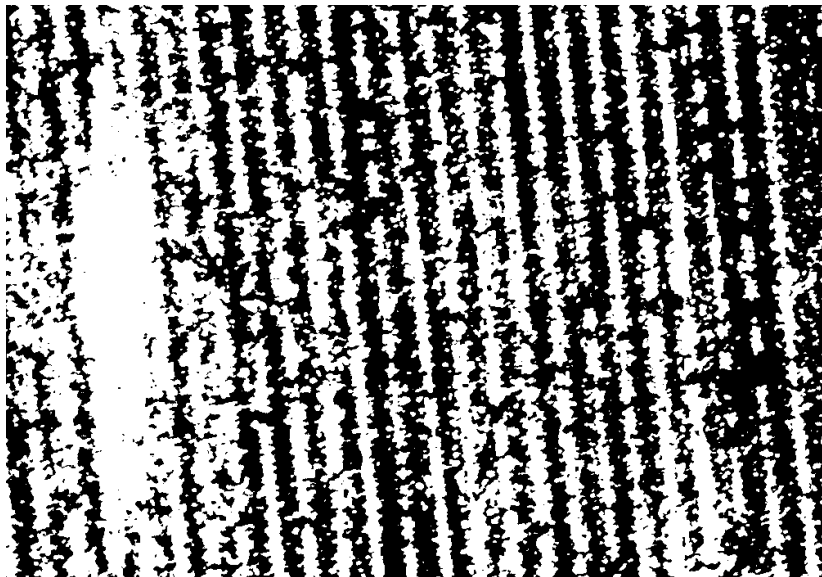
# Combining tiles



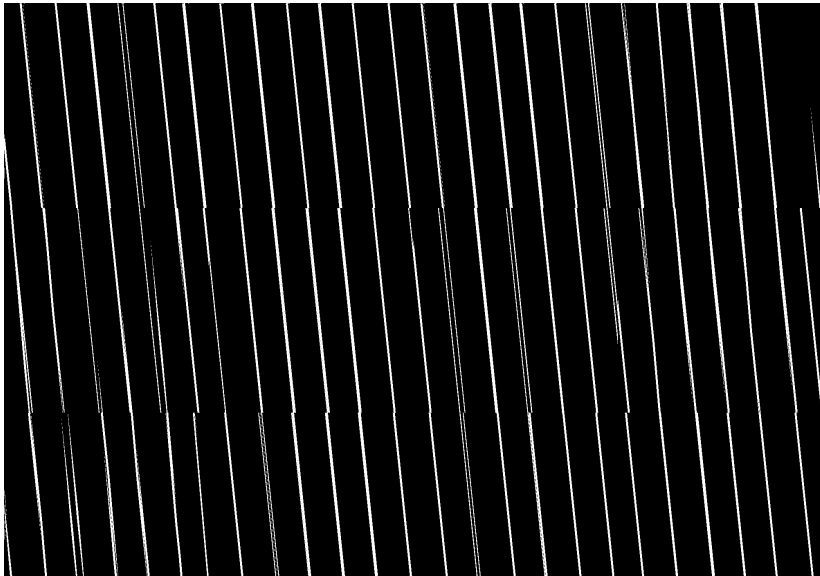
# Cropped mosaic



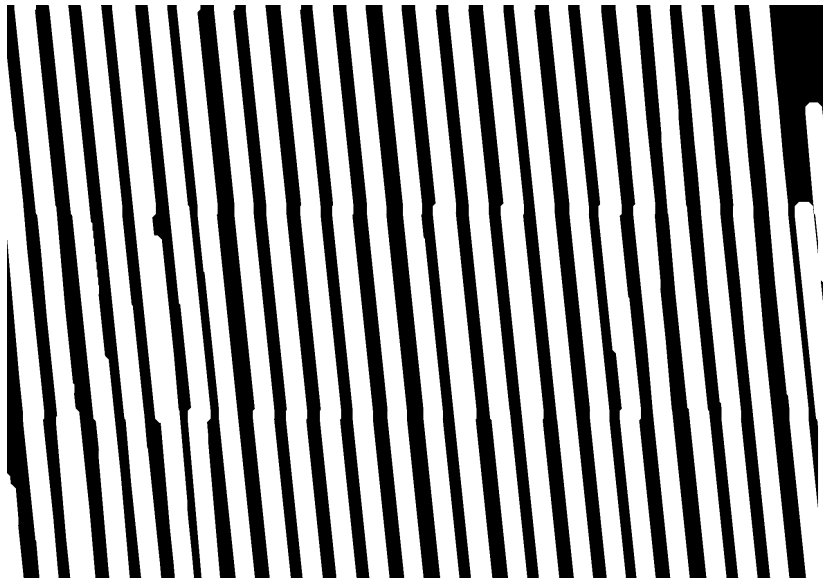
## Segmented mosaic



## Detected crop rows



## Detected crop rows – thickened



# Weed map



# Emphasis on weeds



# Computation transcript

10:29:27 Loading mosaic.

10:29:45 Converting to excess green.

10:29:48 Scan over mosaic.

10:35:15 Writing image with detected crop rows.

10:35:35 Writing weed map mosaic.

10:35:39 Loading mosaic.

10:35:49 Creating map with emphasis on weed patches.

10:36:42 Done.

# Computations

- ▶ Number of analysed tiles
  - ▶  $14 \times 35 = 490$
- ▶ Total computation time
  - ▶ 10 min
- ▶ Platform
  - ▶ Matlab
  - ▶ Intel Core I7-3740QM
  - ▶ 2.7 GHz
  - ▶ 28 GB RAM
  - ▶ Ubuntu 14.04 64 bit

# Conclusion

Given an orthomosaic we can make a weed map through the following actions

- ▶ Split into smaller tiles
- ▶ Locate crop rows in each tile
- ▶ Combine tiles
- ▶ Thicken detected crop rows
- ▶ Remove vegetation in the detected crop rows

# Funding and questions

